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**MONTH YEAR**

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**GRADUATE SCHOOL OF NATURAL & APPLIED SCIENCES**

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**IN**

**DEPARTMENT’S NAME**

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**BY**

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**Supervisor**

**Prof. Dr. Name SURNAME**

**Co-Supervisor (if any)**

**Prof. Dr. Name SURNAME**

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**THESIS TITLE**

submitted by **Name LASTNAME** in partial fulfillment of the requirements for the degree of Master of Science or Doctor of Philosophy in **Name of the Department, Gaziantep University** is approved by,

Assoc. Prof. Dr. Mehmet İshak YÜCE

Director of the Graduate School of Natural and Applied Sciences …………..............

Title Name LASTNAME

Head of the Department of ………… …………..............

Title Name LASTNAME

Supervisor, Name of the Department

Institution or University …………..............

Title Name LASTNAME

Co-Supervisor, Name of the Department

Institution or University …………..............

Graduation Date: 25 February 2021

**Examining Committee Members:**

Title Name LASTNAME

Thesis Supervisor, Name of the Department

Institution or University …………..............

Title Name LASTNAME

Name of the Department

Institution or University …………..............

Title Name LASTNAME

Name of the Department

Institution or University …………..............

Title Name LASTNAME

Name of the Department

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Title Name LASTNAME

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# ABSTRACT

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**Supervisor: Prof. Dr. Name SURNAME**

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Abstract should be in English, contain only 1 paragraph, and not exceed 1 page.

**Key Words:** Keyword 1, Keyword 2, Keyword 3, Keyword 4, Keyword 5.

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# ÖZET

**TEZİN BAŞLIĞI**

**SOYADI, Adı**

**Yüksek Lisans/Doktora Tezi, Bölüm Adı**

**Danışman: Dr. Öğr. Üyesi Adı SOYADI**

**İkinci Danışman: Doç. Dr. Adı SOYADI (varsa)**

**Ay Yıl**

**…. sayfa**

Özet Türkçe ve tek paragraf olmalı, 1 sayfayı geçmemelidir.

**Anahtar Kelimeler:** Anahtar Kelime 1, Anahtar Kelime 2, Anahtar Kelime 3, Anahtar Kelime 4, Anahtar Kelime 5.

***‘’Dedicated to my family’’***

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# LIST OF SYMBOLS

|  |  |
| --- | --- |
| **α** | Alfa |
| **β** | Beta |
| **Ω** | Ohm |
| **π** | Pi |

# LIST OFABBREVIATIONS

|  |  |
| --- | --- |
| **A/D** | Analog to Digital |
| **B-SPM** | Bilinear Static Parametric Model |
| **CE** | Certainty Equivalence |
| **D/A** | Digital to Analog |
| **DC** | Direct Current |
| **DIN** | Dynamic Inertial System |
| **FD** | Fault Detection |
| **FDD** | Fault Detection Diagnosis |
| **FDI** | Fault Detection and Isolation |
| **FTC** | Fault Tolerant Control |
| **g-DIN** | Generalized Dynamic Inertial System |
| **ISE** | Integral Square Error |
| **ISR** | Interrupt Service Routine |
| **LQR** | Linear Quadratic Regulator |
| **LTI** | Linear Time Invariant |
| **MIMO** | Multi Input Multi Output |
| **MRAC** | Model Reference Adaptive Control |
| **MSE** | Mean Square Error |
| **PDJ** | Positive Diagonal Jordan |
| **PEA** | Parametric Eigenstructure Assignment |
| **PSUPA** | Power Supply/Power Amplifier Unit |
| **SISO** | Single Input Single Output |
| **SPR** | Strictly Positive Real |

# CHAPTER I

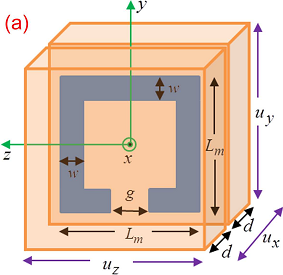
# INTRODUCTION

## 1.1 Motivation of Study

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**Figure 1.1** Equivalent control system block diagram for time-varying gain control equivalent is system block diagram for time-varying gains.

There are wide varieties of control methods in FTC and an extensive research is still conducted. However the lack of a systematical approach is still an open problem. The equation sample can be given as follows:

 (1.1)

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(1.2)

**Table 1.1** Process parameters

|  |  |
| --- | --- |
| **Parameters** | **Value** |
| Tank height, *hmax* | 25 cm |
| Pomp voltage level | 0-5 V |
| Bottom area, Tank1, Tank2, *A1*, *A2* | 0.01389 m2 |
| Bottom area, Tank3, Tank4, *A3*, *A4* | 0.01389 m2 |
| Out pipe cross-sectional area, *a1,a3,,a2,a4* | 50.26e-6 m2 |
| Pomp constant, *k* | 2.2e-3 lt/Vs |
| Tank1 operating point level *h1o* | 8.0 cm |
| Tank2 operating point level *h2o* | 5.0 cm |
| Tank3 operating point level *h3o* | 1.5 cm |

**Table 1.2** System operating point

|  |  |  |
| --- | --- | --- |
| Control Method | Output1 ISE | Output2 ISE (×103) |
| Design I | 391.59 | 1.0151 |
| Design II | 389.58 | 0.6418 |
| Design III | 379.61 | 0.0001 |

# 

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